# Computable Real Analysis without Set Theory or Turing Machines

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Canadian Mathematical Society Calgary, Monday 5 June 2006

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# **Topological spaces**

A topological space is a set *X* (of points) equipped with a set of ("open") subsets of *X* closed under finite intersection and arbitrary union.

# Wood and chipboard

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Chipboard is a set *X* of particles of sawdust equipped with a quantity of glue that causes the sawdust to form a cuboid.

# A natural language for topology

I shall introduce a language for general topology and (in particular) real analysis that looks like set theory.

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As the title says, it's not set theory.

# A natural language for topology

I shall introduce a language for general topology and (in particular) real analysis that looks like set theory. As the title says, it's not set theory.

It looks like set theory because

- there are analogies between sets and spaces
- these analogies can be formulated as universal properties in category theory
- universal properties can be expressed as introduction and elimination rules in proof theory.

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I will tell this story in Kananaskis on Wednesday.

This is not a Theorem (*à la* Brouwer) but a design principle. The language only introduces continuous computable functions.

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In particular, all functions  $\mathbb{R} \times \mathbb{R} \to \Sigma$  are continuous and correspond to open subspaces.

This is not a Theorem (*à la* Brouwer) but a design principle. The language only introduces continuous computable functions.

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In particular, all functions  $\mathbb{R} \times \mathbb{R} \to \Sigma$  are continuous and correspond to open subspaces.

Hence a < b, a > b and  $a \neq b$  are definable,

but  $a \le b$ ,  $a \ge b$  and a = b are not definable.

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In particular, all functions  $\mathbb{R} \times \mathbb{R} \to \Sigma$  are continuous and correspond to open subspaces.

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 $\mathbb{N}$  and  $\mathbb{Q}$  are discrete and Hausdorff.

So we have all six relations for them.

#### Geometric, not Intuitionistic, logic

A term  $\sigma$  :  $\Sigma$  is called a proposition.

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- We can form  $\phi \land \psi$  and  $\phi \lor \psi$ .
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But not  $\exists x : X$ .  $\phi x$  for arbitrary X — it must be overt.

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A term  $\sigma : \Sigma$  is called a proposition. A term  $\phi : \Sigma^X$  is called a predicate or open subspace. Applicatio  $\phi a$  denotes membership of an open subspace. We can form  $\phi \land \psi$  and  $\phi \lor \psi$ . Also  $\exists n : \mathbb{N}. \phi x, \exists q : \mathbb{Q}. \phi x, \exists x : \mathbb{R}. \phi x \text{ and } \exists x : [0,1]. \phi x.$ But not  $\exists x : X. \phi x$  for arbitrary X — it must be overt.

Negation and implication are not allowed.

Because:

- this is the logic of open subspaces;
- ▶ the function  $\odot \Leftrightarrow \bullet$  on  $\begin{pmatrix} \odot \\ \bullet \end{pmatrix}$  is not continuous;

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• the Halting Problem is not solvable.

#### Compactness and universal quantification

When  $K \subset X$  is compact (*e.g.*  $[0, 1] \subset \mathbb{R}$ ), we can form  $\forall x \colon K. \phi x$ .

$$\frac{\Gamma, x: K \vdash \top \Leftrightarrow \phi x}{\Gamma \vdash \top \Leftrightarrow \forall x: K. \phi x}$$

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From the usual "finite open subcover" definition of compactness, this captures the notion of cover,  $K \subset U$ .

#### Compactness and exchanging quantifiers

The quantifier is a (higher-type) function  $\forall_K : \Sigma^K \to \Sigma$ .

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Like everything else, it's Scott continuous.

This captures the *infinitary* part

of the "finite open subcover" definition.

#### Compactness and exchanging quantifiers

The quantifier is a (higher-type) function  $\forall_K : \Sigma^K \to \Sigma$ . Like everything else, it's Scott continuous. This captures the *infinitary* part of the "finite open subcover" definition.

The useful cases of this in real analysis are

$$\forall x : K. \exists \delta > 0.\phi(x, \delta) \iff \exists \delta > 0.\forall x : K.\phi(x, \delta)$$
  
$$\forall x : K. \exists n.\phi(x, n) \iff \exists n.\forall x : K.\phi(x, n)$$

in the case where  $(\delta_1 < \delta_2) \land \phi(x, \delta_2) \Rightarrow \phi(x, \delta_1)$ or  $(n_1 > n_2) \land \phi(x, n_2) \Rightarrow \phi(x, n_1).$ 

Recall that uniform convergence, continuity, *etc.* involve commuting quantifiers like this.

# Examples: continuity and uniform continuity Recall that, from local compactness of $\mathbb{R}$ ,

$$\phi x \Leftrightarrow \exists \delta > 0. \ \forall y \colon [x \pm \delta]. \ \phi y$$

Theorem: Every definable function  $f : \mathbb{R} \to \mathbb{R}$  is continuous:

$$\epsilon > 0 \implies \exists \delta > 0. \ \forall y \colon [x \pm \delta]. (|fy - fx| < \epsilon)$$

Proof: Put  $\phi_{x,\epsilon}y \equiv (|fy - fx| < \epsilon)$ , with parameters  $x, \epsilon : \mathbb{R}$ . Theorem: Every function f is uniformly continuous on any compact subspace  $K \subset \mathbb{R}$ :

$$\epsilon > 0 \implies \exists \delta > 0. \ \forall x \colon K. \ \forall y \colon [x \pm \delta]. (|fy - fx| < \epsilon)$$

**Proof:**  $\exists \delta > 0$  and  $\forall x : K$  commute.

#### Example: Dini's theorem

**Theorem:** Let  $f_n : K \to \mathbb{R}$  be an increasing sequence of functions

 $n: \mathbb{N}, x: K \vdash f_n x \leq f_{n+1} x: \mathbb{R}$ 

that converges pointwise to  $g: K \to \mathbb{R}$ , so

$$\epsilon > 0, x : K \vdash \top \Leftrightarrow \exists n. gx - f_n x < \epsilon.$$

If *K* is compact then  $f_n$  converges to *g* uniformly.

Proof: Using the introduction and Scott continuity rules for  $\forall$ ,

$$\epsilon > 0 \vdash \top \quad \Leftrightarrow \quad \forall x \colon K. \ \exists n. gx - f_n x < \epsilon$$
$$\Leftrightarrow \quad \exists n. \forall x \colon K. \ gx - f_n x < \epsilon$$

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#### Exercise for everyone!

Make a habit of trying to formulate statements in analysis according to (the restrictions of) the ASD language.

This may be easy — it may not be possible

The exercise of doing so may be 95% of solving your problem!

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#### Constructive intermediate value theorem

Suppose that  $f : \mathbb{R} \to \mathbb{R}$  doesn't hover, *i.e.* 

$$b, d : \mathbb{R} \vdash b < d \implies \exists x. (b < x < d) \land (fx \neq 0),$$

and f0 < 0 < f1. Then fc = 0 for some 0 < c < 1.

Interval trisection: Let  $a_0 \equiv 0$ ,  $e_0 \equiv 1$ ,

$$b_n \equiv \frac{1}{3}(2a_n + e_n)$$
 and  $d_n \equiv \frac{1}{3}(a_n + 2e_n)$ .

Then  $f(c_n) \neq 0$  for some  $b_n < c_n < d_n$ , so put

$$a_{n+1}, e_{n+1} \equiv \begin{cases} a_n, c_n & \text{if } f(c_n) > 0 \\ c_n, e_n & \text{if } f(c_n) < 0. \end{cases}$$

Then  $f(a_n) < 0 < f(e_n)$  and  $a_n \rightarrow c \leftarrow e_n$ . (This isn't the ASD proof/algorithm yet!)

#### Stable zeroes

The interval trisection finds zeroes with this property:



Definition: c :  $\mathbb{R}$  is a stable zero of f if

$$\begin{array}{ll} a,e: \mathbb{R} \ \vdash \ a < c < e \ \Rightarrow \ \exists bd. & (a < b < c < d < e) \\ & \wedge & (fb < 0 < fd \ \lor fb > 0 > fd). \end{array}$$

The subspace  $Z \subset [0, 1]$  of all zeroes is compact. The subspace  $S \subset [0, 1]$  of stable zeroes is overt (as we shall see...)

#### Straddling intervals

An open subspace  $U \subset \mathbb{R}$  contains a stable zero  $c \in U \cap S$  iff U also contains a straddling interval,

 $[b,d] \subset U$  with fb < 0 < fd or fb > 0 > fd.

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 $[\Rightarrow]$  From the definitions.  $[\leftarrow]$  The straddling interval is an intermediate value problem in miniature.

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 $[\Rightarrow]$  From the definitions.  $[\Leftarrow]$  The straddling interval is an intermediate value problem in miniature.

Notation: Write  $\diamond U$  if *U* contains a straddling interval. We write this containment in ASD using the universal quantifier.

$$\diamond \phi \equiv \exists bd. \qquad (\forall x : [b, d]. \phi x) \\ \land \quad (fb < 0 < fd) \lor (fb > 0 > fd).$$

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### The possibility operator

- By hypothesis,  $\Diamond(0, 1) \Leftrightarrow \top$ , whilst  $\Diamond \emptyset \Leftrightarrow \bot$  trivially.
- $\diamond \bigcup_{i \in I} U_i \iff \exists i. \diamond U_i.$
- If  $f : \mathbb{R} \to \mathbb{R}$  is an open map, this is easy.
- If  $f : \mathbb{R} \to \mathbb{R}$  doesn't hover, it depends on connectedness of  $\mathbb{R}$ .

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**Definition:** A term  $\diamond$  :  $\Sigma^{\Sigma^X}$  with this property is called an overt subspace of *X*.

A simpler example: For any point *a* : *X*, the neighbourhood filter  $\diamond \equiv \eta a \equiv \lambda \phi$ .  $\phi a$  is a possibility operator.

 $\diamond$  is a point iff it also preserves  $\top$  and  $\land$ .

#### The Possibility Operator as a Program

Theorem: Let  $\diamond$  be an overt subspace of  $\mathbb{R}$  with  $\diamond \top \Leftrightarrow \top$ . Then  $\diamond$  has an accumulation point  $c \in \mathbb{R}$ , *i.e.* one of which every open neighbourhood  $c \in U \subset \mathbb{R}$ satisfies  $\diamond U$ :

 $\phi: \Sigma^{\mathbb{R}} \vdash \phi c \Rightarrow \diamond \phi$ 

**Example:** In the intermediate value theorem, any such *c* is a stable zero.

Proof: Interval trisection.

Corollary: Obtain a Cauchy sequence from a Dedekind cut.

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## Possibility operators classically

Define  $\diamond U$  as  $U \cap S \neq \emptyset$ , for any subset  $S \subset X$  whatever. Then  $\diamond (\bigcup_{i \in I} U_i)$  iff  $\exists i. \diamond U_i$ . Conversely, if  $\diamond$  has this property, let

$$S \equiv \{a \in X \mid \text{for all open } U \subset X, \quad a \in U \Rightarrow \diamond U\}$$
$$W \equiv X \setminus S = \bigcup \{U \text{ open } \mid \neg \diamond U\}$$

Then *W* is open and *S* is closed.  $\neg \diamond W$  by preservation of unions. Hence  $\diamond U$  holds iff  $U \notin W$ , *i.e.*  $U \cap S \neq \emptyset$ .

If  $\diamond$  had been derived from some *S*' then *S* =  $\overline{S'}$ , its closure.

Classically, every (sub)space *S* is overt.

### Necessity operators

Let  $K \subset \mathbb{R}$  be any compact subspace.

(For example, all zeroes in a bounded interval.)

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 $U \mapsto (K \subset U)$  is Scott continuous.

**Notation:** Write  $\Box \phi$  for  $\forall x : K. \phi x$ .

#### Modal operators, separately

□ encodes the compact subspace  $Z \equiv \{x \in \mathbb{I} \mid fx = 0\}$  of all zeroes.  $\diamond$  encodes the overt subspace *S* of stable zeroes.

> $\Box X \text{ is true} \quad \text{and} \quad \Box U \land \Box V \implies \Box (U \cap V)$  $\Diamond \emptyset \text{ is false} \quad \text{and} \quad \Diamond (U \cup V) \implies \Diamond U \lor \Diamond V.$

> > $(Z \neq \emptyset)$  iff  $\Box \emptyset$  is false  $(S \neq \emptyset)$  iff  $\Diamond \mathbb{R}$  is true

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#### Modal operators, together

 $\diamond$  and  $\Box$  for the subspaces  $S \subset Z$  are related in general by:

 $\Box U \land \diamond V \implies \diamond (U \cap V)$  $\Box U \iff (U \cup W = X)$  $\diamond V \implies (V \notin W)$ 

*S* is dense in *Z* iff

 $\Box(U \cup V) \; \Rightarrow \; \Box \; U \lor \diamond V$ 

 $\diamond V \iff (V \not\subset W)$ 

In the intermediate value theorem for functions that don't hover (*e.g.* polynomials):

- S = Z in the non-singular case
- $S \subset Z$  in the singular case (*e.g.* double zeroes).

#### Modal laws in ASD notation

Overt subspaceCompact subspace $\Diamond \perp \Leftrightarrow \bot$  $\Box \top \Leftrightarrow \top$  $\Diamond (\phi \lor \psi) \Leftrightarrow \Diamond \phi \lor \Diamond \psi$  $\Box (\phi \land \psi) \Leftrightarrow \Box \phi \land \Box \psi$  $\sigma \land \Diamond \phi \Leftrightarrow \Diamond (\sigma \land \phi)$  $\sigma \lor \Box \phi \Leftrightarrow \Box (\lambda x. \sigma \lor \phi x)$ 

Commutative laws:

ive laws:  

$$\left( \lambda x. \left( \lambda y. \phi xy \right) \right) \iff \left( \lambda y. \left( \lambda x. \phi xy \right) \right)$$

$$\Box \left( \lambda x. \Box (\lambda y. \phi xy) \right) \iff \Box \left( \lambda y. \Box (\lambda x. \phi xy) \right)$$

Mixed modal laws for a compact overt subspace.

 $\Box \phi \lor \diamond \psi \leftarrow \Box (\phi \lor \psi) \quad \text{and} \quad \Box \phi \land \diamond \psi \Rightarrow \diamond (\phi \land \psi)$ 

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# Empty/inhabited is decidable

Theorem: Any compact overt subspace  $(\Box, \diamond)$  is either empty  $(\Box \perp)$  or non-empty  $(\diamond \top)$ .

Proof:

$\Diamond \top \Leftrightarrow \bot$	empty	$\Box\bot  \Leftrightarrow  \top$
$\Diamond \top \Leftrightarrow \top$	inhabited	$\Box\bot  \Leftrightarrow  \bot$
$\Box \bot \lor \Diamond \top \Leftarrow$	complementary	$\Box \bot \land \Diamond \top \Rightarrow$
$\Box(\bot \lor \top) \Leftrightarrow \Box \top \Leftrightarrow$	imes (mixed) $◊(⊥$	$\wedge \bot) \Leftrightarrow \Diamond \bot \Leftrightarrow \bot$

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#### Proof:

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$\Diamond \top \Leftrightarrow \top$	inhabited	$\Box\bot  \Leftrightarrow  \bot$
$\Box \bot \lor \Diamond \top \Leftarrow$	complementary	$\Box \bot \land \Diamond \top \Rightarrow$
$\Box(\bot \lor \top) \Leftrightarrow \Box \top \Leftrightarrow$	T (mixed) $\Diamond$ (⊥	$\wedge \bot) \Leftrightarrow \Diamond \bot \Leftrightarrow \bot$

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The dichotomy (either  $\Box \perp$  or  $\Diamond \top$ ) means that the parameter space  $\Gamma$  is a disjoint union.

So, if it is connected, like **R**<sup>n</sup>, something must break at singularities.

It is the modal law  $\Box(\phi \lor \psi) \Rightarrow \Box \phi \lor \diamond \psi$ .

Non-empty compact overt subspace of  $\mathbb{R}$  has a maximum

**Theorem:** Any overt compact subspace  $K \subset \mathbb{R}$  is

- either empty
- or has a greatest element,  $\max K \in K$ .

**Definition:** max *K* satisfies, for  $x : \mathbb{R}$ ,

 $\Gamma \vdash \max K \leq x$ 

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Compact overt subspace of  $\mathbb{R}$  has a maximum Proof: Define a Dedekind cut (next slide)

 $\delta d \equiv \exists k \colon K. \ d < k \text{ and } vu \equiv \forall k \colon K. \ k < u$ 

Hence there is some  $a : \mathbb{R}$  with

 $\delta d \Leftrightarrow (d < a)$  and  $vu \Leftrightarrow (a < u)$ 

Moreover,  $a \in K$ .

*K* is also the **closed** subspace co-classified by  $\omega x \equiv \Box(\lambda k. x \neq k)$ , so we must show that  $\omega a \Leftrightarrow \bot$ .

$$\omega a \equiv \Box(\lambda k. a \neq k) \iff \Box(\lambda k. a < k) \lor (k < a)$$
  
$$\Rightarrow \diamond(\lambda k. a < k) \lor \Box(\lambda k. k < a)$$
  
$$\equiv \delta a \lor v a$$
  
$$\Leftrightarrow (a < a) \lor (a < a) \Leftrightarrow \bot.$$

#### Compact overt subspace of $\mathbb{R}$ defines a Dedekind cut

Overt subspace ◊ Compact subspace  $\Box$  $\perp, \lor, \lor$  and so  $\exists_{\mathbb{R}}$ commutes with  $\top$ ,  $\land$  and  $\bigvee$  $\delta d \equiv \Diamond (\lambda k. d < k)$ Dedekind cut  $vu \equiv \Box(\lambda k. k < u)$  $(d < e) \land \delta e \equiv$ lower/upper  $vt \wedge (t < u) \equiv$  $(d < e) \land \Diamond(\lambda k. e < k)$  $\Box(\lambda k. \, k < t) \land (t < u)$  $\Leftrightarrow \Diamond (\lambda k. d < e < k)$  $\Leftrightarrow \Box(\lambda k. k < t < u)$ (Frobenius/ $\Box$   $\top$ )  $\Rightarrow \Box(\lambda k. k < u) \equiv vu$  $\Rightarrow \Diamond (\lambda k. d < k) \equiv \delta d$ (transitivity) rounded (interpolation) ⇐  $\Leftarrow$  $\exists d. \, \delta d \equiv \exists d. \, \Diamond (\lambda k. \, d < k)$ inhabited  $\exists u. vu \equiv \exists u. \Box(\lambda k. k < u)$  $\Leftrightarrow \Diamond (\lambda k. \exists d. d < k)$ (directed joins)  $\Leftrightarrow \Box(\lambda k, \exists u, k < u)$  $\Leftrightarrow \Diamond \top \Leftrightarrow \neg$  (inhabited) (extrapolation)  $\Leftrightarrow$   $\Pi$  T  $\Leftrightarrow$  T

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# The Bishop-style proof

**Definition:** *K* is totally bounded if, for each  $\epsilon > 0$ , there's a finite subset  $S_{\epsilon} \subset K$  such that  $\forall x : K. \exists y \in S_{\epsilon}. |x - y| < \epsilon.$ 

Proof: If *K* is closed and totally bounded,

- either the set *S*<sub>1</sub> is empty, in which case *K* is empty too,
- or  $x_n \equiv \max S_{2^{-n}}$  defines a Cauchy sequence that converges to max *K*.

But *K* is also overt, with  $\diamond \phi \equiv \exists \epsilon > 0. \exists y \in S_{\epsilon}. \phi y.$ 

**Definition:** *K* is located if, for each  $x \in X$ , inf { $|x - k| | k \in K$ } is defined. (A different usage of the word "located".) closed, totally bounded  $\Rightarrow$  compact and overt  $\Rightarrow$  located (in TTE) also r.e. closed

- Total boundedness and locatedness are metrical concepts.
- Compactness and overtness are topological.

# The real interval is connected (usual proof)

Any closed subspace of a compact space is compact. Any open subspace of an overt space is overt.

Any clopen subspace of an overt compact space is overt compact, so it's either empty or has a maximum.

Since the clopen subspace is open, its elements are interior, so the maximum can only be the right endpoint of the interval.

Any clopen subspace has a clopen complement.

- They can't both be empty, but
- in the interval they can't both have maxima (the right endpoint).

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Hence one is empty and the other is the whole interval.

#### Connectedness in modal notation

We have just proved

 $\Diamond(\phi \land \psi) \Leftrightarrow \bot, \Box(\phi \lor \psi) \Leftrightarrow \top \vdash \Box \phi \lor \Box \psi \Leftrightarrow \top$ 

where  $\Box \theta \equiv \forall x : [0, 1]$ .  $\theta x$  and  $\Diamond \theta \equiv \exists x : [0, 1]$ .  $\theta x$ .

Using the mixed modal law  $\diamond \phi \land \Box \psi \Rightarrow \diamond (\phi \land \psi)$ and the Gentzen-style rules

$$\begin{array}{c} \sigma \Leftrightarrow \top \vdash \alpha \Rightarrow \beta \\ \hline \\ \vdash \sigma \land \alpha \Rightarrow \beta \end{array} \qquad \begin{array}{c} \sigma \Leftrightarrow \bot \vdash \alpha \Rightarrow \beta \\ \hline \\ \vdash \alpha \Rightarrow \beta \lor \sigma \end{array}$$

connectedness may be expressed in other ways:

#### Weak intermediate value theorems

Let  $f : [0,1] \rightarrow \mathbb{R}$ , and use two of these forms of connectedness.

Put  $\phi x \equiv (0 < fx)$  and  $\psi x \equiv (fx < 0)$ . Use  $(\phi \land \psi) = \bot \vdash \Box(\phi \lor \psi) \land (\phi \land \psi) \Rightarrow \bot$ .  $(\phi \land \psi) \Leftrightarrow \bot$  by disjointness. Then  $(f0 < 0 < f1) \land (\forall x : [0, 1]. fx \neq 0) \Leftrightarrow \bot$ . So the closed, compact subspace  $Z \equiv \{x : \mathbb{I} \mid fx = 0\}$  is not empty.

Put  $\phi x \equiv (e < fx)$  and  $\psi x \equiv (fx < t)$ . Use  $\Box(\phi \lor \psi) \land \Diamond \phi \land \Diamond \psi \Rightarrow \Diamond(\phi \land \psi)$ .  $\Box(\phi \lor \psi)$  by locatedness. Then  $(f0 < e < t < f1) \Rightarrow (\exists x : [0,1]. e < fx < t)$ . or  $\epsilon > 0 \vdash \exists x. |fx| < \epsilon$ .

So the open, overt subspace  $\{x \mid e < fx < t\}$  is inhabited.

# Straddling intervals in ASD

Let  $f : [0, 1] \rightarrow \mathbb{R}$  be a function that doesn't hover.

**Proposition:**  $\diamond$  preserves joins,  $\diamond(\exists n. \theta_n) \Leftrightarrow \exists n. \diamond \theta_n$ . **Proof:** Consider  $\phi^{\pm}x \equiv \exists n. \exists y. (x < y < u) \land (fy < 0) \land \forall z: [x, y]. \theta_n z$ . Then  $\exists x. \phi^+ x \land \phi^- x$  by connectness.

**Lemma:** 0 < a < 1 is a stable zero of *f* iff it is an accumulation point of  $\diamond$ , *i.e.*  $\phi a \Rightarrow \diamond \phi$ .

**Theorem:**  $\diamond$  and  $\Box$  obey  $\Box \phi \land \diamond \psi \Rightarrow \diamond (\phi \land \psi)$ .

They also obey  $\Box(\phi \lor \psi) \Rightarrow \Box \phi \lor \diamond \phi$ iff *f* doesn't touch the axis without crossing it.

When f is a polynomial, this is the non-singular case, where f has no zeroes of even multiplicity.

# Solving equations in ASD

In the non-singular case, all zeroes are stable, ◊ and □ define a non-empty overt compact subspace, which has a maximum.

So the classical textbook proof of IVT,

```
a \equiv \sup \{x : [0,1] \mid fx \le 0\},\
```

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is computationally meaningful!

The interval trisection algorithm for ◊ finds some zero, even in the singular case, but it behaves non-deterministically and catastrophically.

#### Parametric solutions

The set of zeroes varies discontinuously at singularities in the parameters.

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For example, the cubic equation may have

- three real stable zeroes (on one stable region),
- one stable zero and an unstable (double) zero,
- just one stable zero (in the other stable region).

The modal operators □ and ◊ are Scott-continuous throughout the parameter space.

The only thing that goes wrong at the singularity is that one of the mixed modal laws fails.